

Designation	Symbol	Unit	Motor type MDD ...				
			112 A-N-040	112 B-N-040	112 C-N-040	112 D-N-040	112 C-N-060
Nominal motor speed <sup>1)</sup>	$n$	min <sup>-1</sup>	4000	4000	4000	4000	6000
Continuous torque at standstill <sup>2)</sup>	$M_{dN}$	Nm	10.5(13.0) <sup>5)</sup>	17.5(29.0) <sup>5)</sup>	28.0(44.0) <sup>5)</sup>	38.0(44.2) <sup>5)</sup>	28.0(32.9) <sup>5)</sup>
Continuous current at standstill	$I_{dN}$	A	23.0(28.4) <sup>5)</sup>	41.5(68.8) <sup>5)</sup>	58.1(91.3) <sup>5)</sup>	88.4(102.9) <sup>5)</sup>	87.5(102.9) <sup>5)</sup>
Theor. maximum torque <sup>3)</sup>	$M_{max}$	Nm	31.3	65.5	100.1	132.2	77.0
Peak current	$I_{max}$	A	72.9	166.4	222.2	329.1	257.4
Rotor moment of inertia <sup>4)</sup>	$J_M$	kgm <sup>2</sup>	$61 \times 10^{-4}$	$120 \times 10^{-4}$	$170 \times 10^{-4}$	$230 \times 10^{-4}$	$170 \times 10^{-4}$
Torque constant at 20 °C	$K_m$	Nm/A	0.46	0.42	0.48	0.43	0.32
Windings resistance at 20 °C	$R_A$	Ohm	0.38	0.11	0.08	0.05	0.04
Windings inductance	$L_A$	mH	4.0	1.5	0.9	0.7	0.5
Thermal time constant	$T_{th}$	min	100 (75) <sup>5)</sup>	90 (60) <sup>5)</sup>	100 (75) <sup>5)</sup>	120 (90) <sup>5)</sup>	100 (75) <sup>5)</sup>
Mass <sup>4)</sup>	$m_M$	kg	25	36	48	59	48

<sup>1)</sup> Usable motor speed is determined by the torque requirements of the application. The usable speed  $n_{max}$  found in the selection lists of the motor-drive combinations are binding for **standard applications**. The usable speed for other applications can be found using the required torque in the torque-speed characteristics curves  
<sup>2)</sup> With 60 K overtemperature at the motor housing.  
<sup>3)</sup> Achievable maximum torque is dependent upon the drive used. Only those maximum torques  $M_{max}$  found in the selection list of the motor-drive combinations are binding.  
<sup>4)</sup> Without blocking brake, without blower  
<sup>5)</sup> Parenthetical values apply to motors with surface cooling.

Fig 10.1: Type dependent motor data

Designation	Symbol	Unit	Data
Permissible ambient temperature	$T_{um}$	°C	0 ... + 45
Permissible storage and transport temperature	$T_L$	°C	-20 ... + 80
Maximum installation elevation		m	1000 meters above sea level
Protection category			IP 65
Insulation classification			F
Housing coat			Black prime coat (RAL 9005)

Fig 10.2: General data - MDD 112

Designation	Symbol	Unit	Data Blocking Brake		
Principle of action			electrically actuated release		
Blocking brake	$M_B$	Nm		144,060	
Nominal voltage	$U_N$	V	DC 24 ± 10%	DC 24 ± 10%	DC 24 ± 10%
Nominal current	$I_N$	A	0.75	1.35	1.35
Moment of inertia	$J_B$	kgm <sup>2</sup>	$3.6 \times 10^{-4}$	$32 \times 10^{-4}$	$32 \times 10^{-4}$
Release delay	$t_L$	ms	70	150	150
Clamping delay	$t_K$	ms	30	30	30
Mass	$m_B$	kg	1.1	3.5	3.5

Fig 10.3: Technical data - blocking brake

## 10.2. Torque-Speed Characteristics

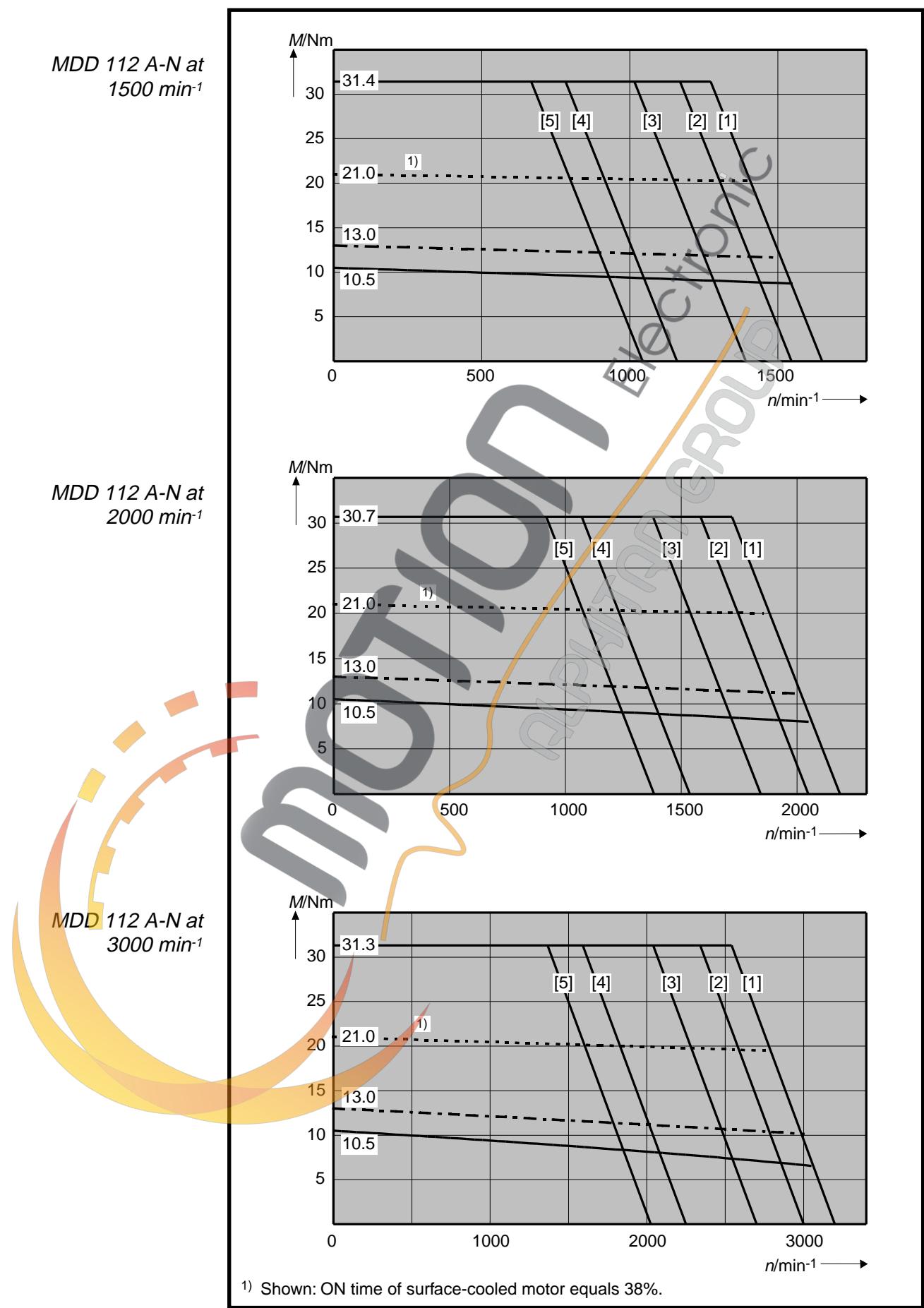


Fig 10.4: Torque-speed characteristics curve MDD 112

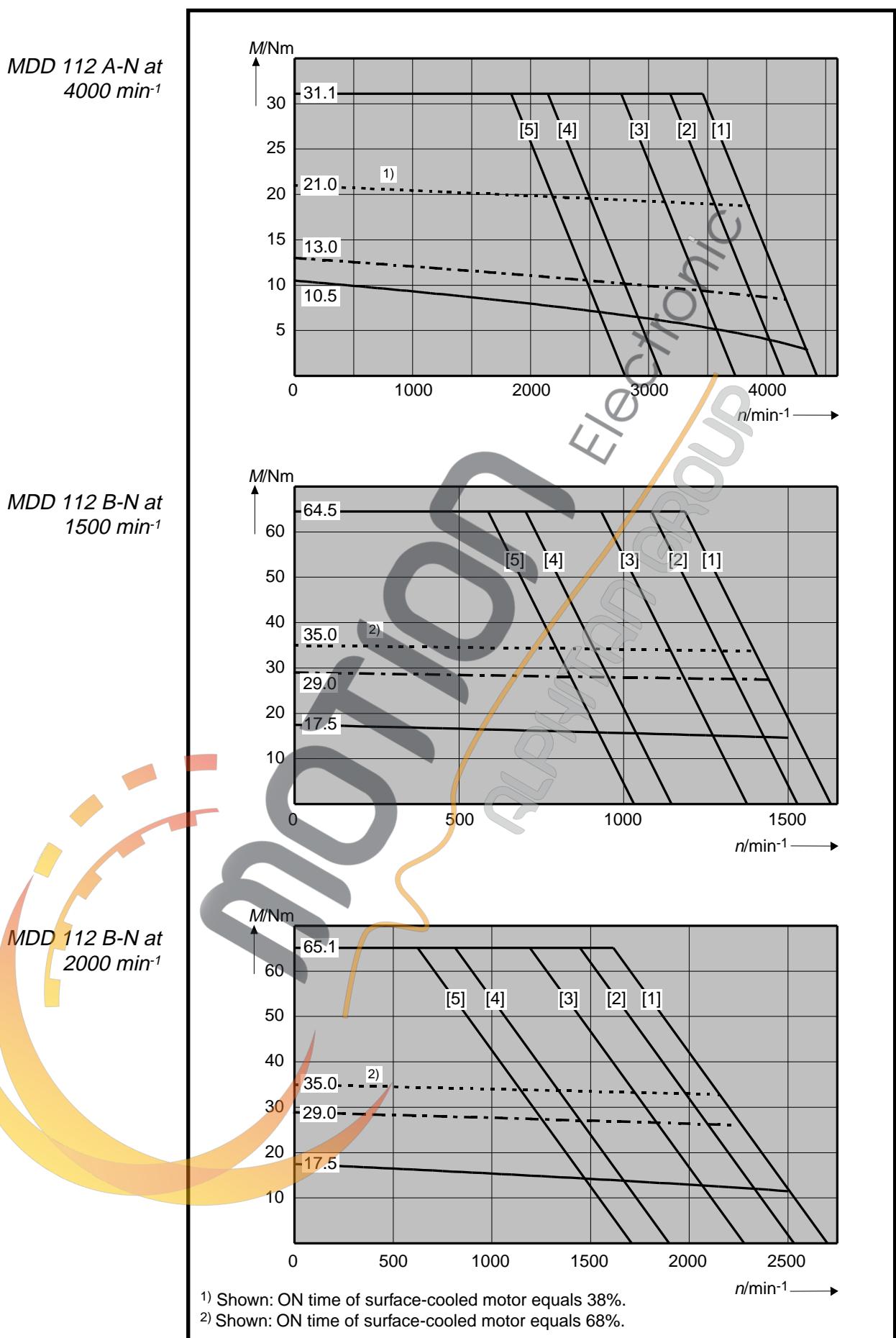
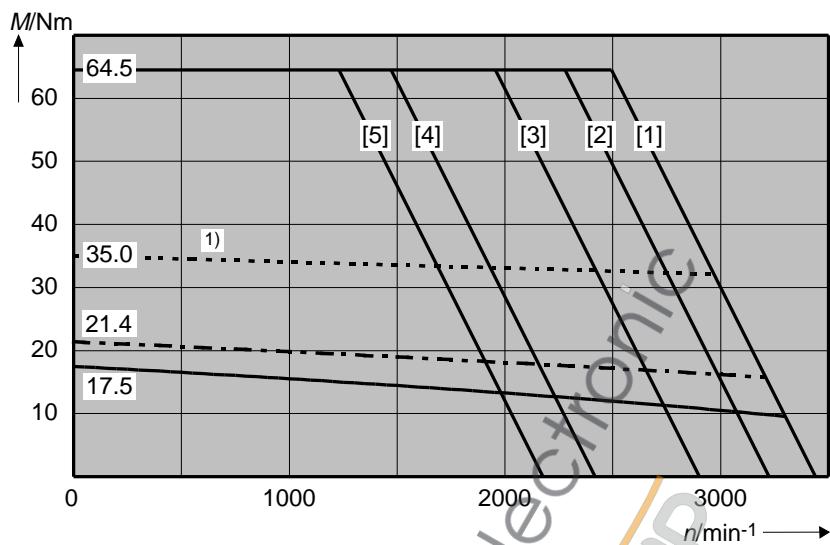
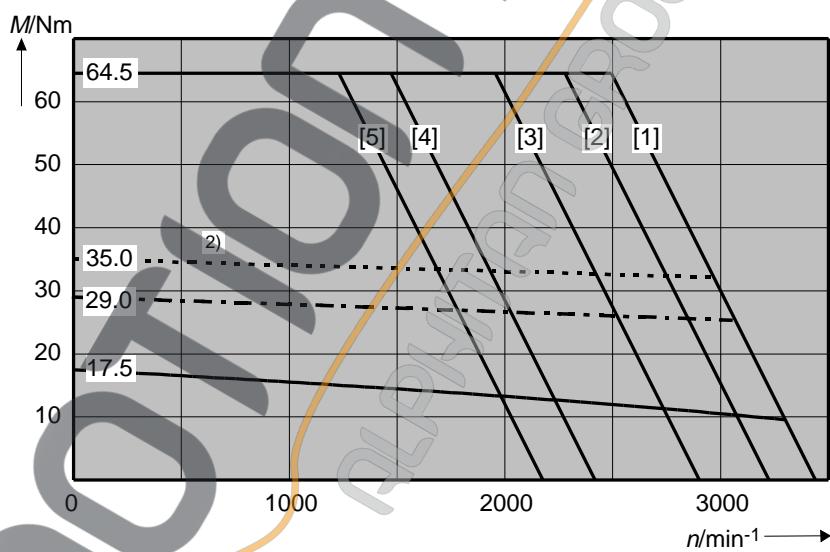


Fig 10.5: Torque-speed characteristics curve MDD 112

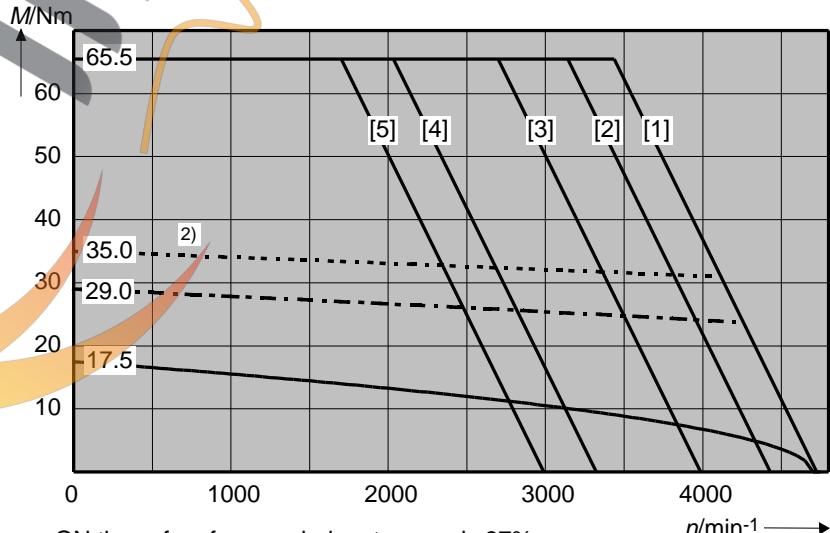
MDD 112 B-N at  
3000 min<sup>-1</sup>



MDD 112 B-L at  
3000 min<sup>-1</sup>



MDD 112 B-N at  
4000 min<sup>-1</sup>



<sup>1)</sup> Shown: ON time of surface-cooled motor equals 37%.

<sup>2)</sup> Shown: ON time of surface-cooled motor equals 69%.

Fig 10.6: Torque-speed characteristics curve MDD 112

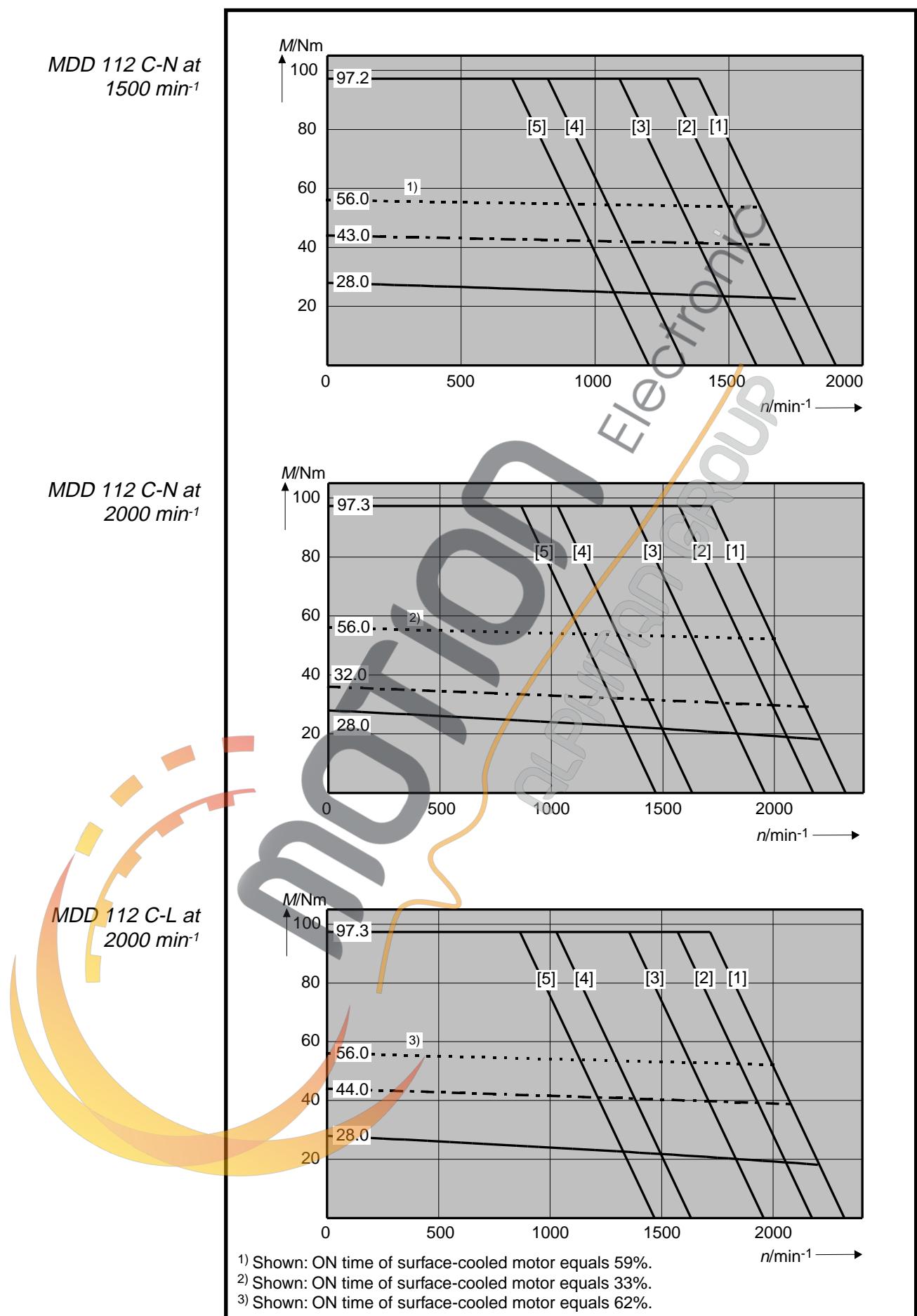


Fig 10.7: Torque-speed characteristics curve MDD 112

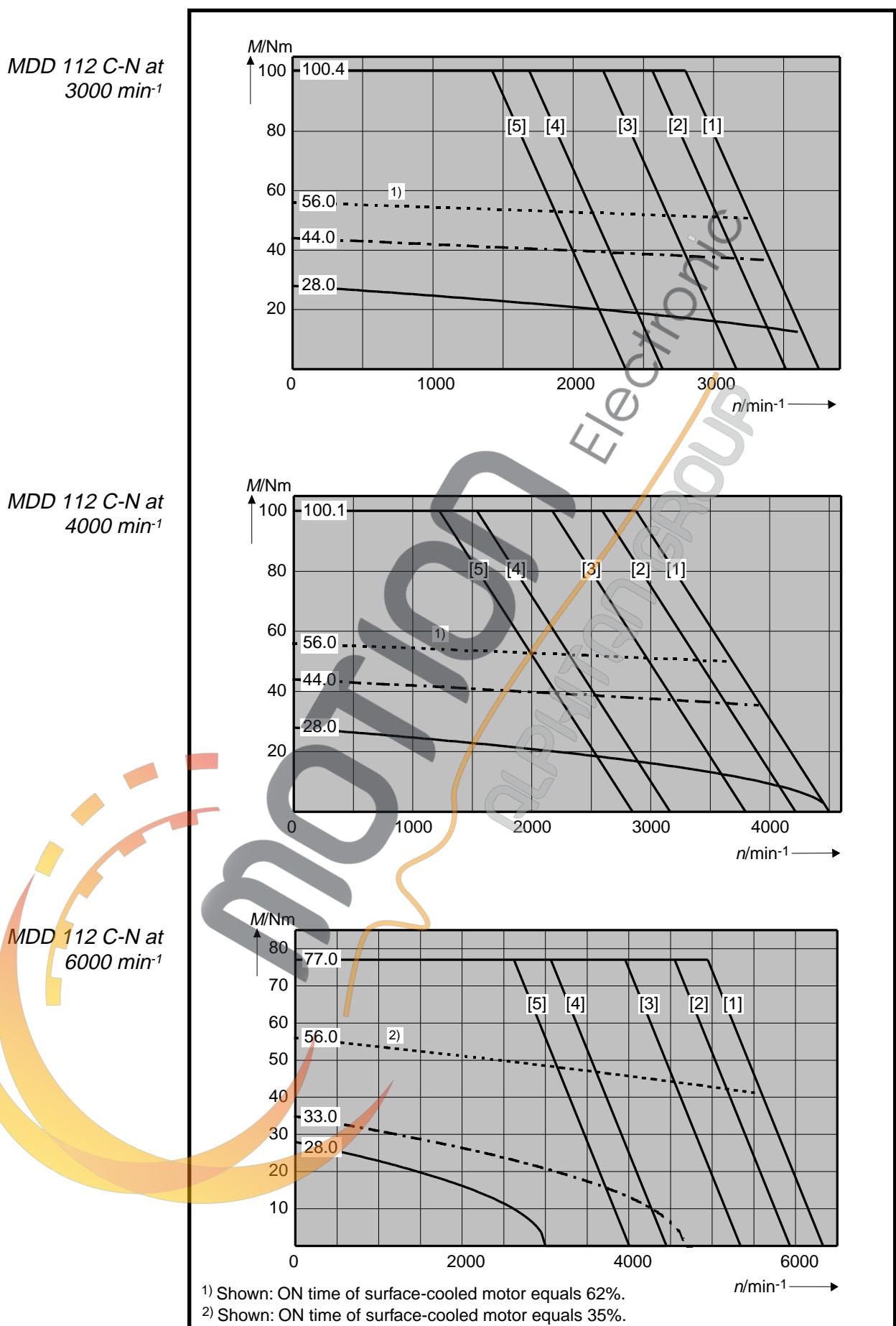


Fig 10.8: Torque-speed characteristics curve MDD 112

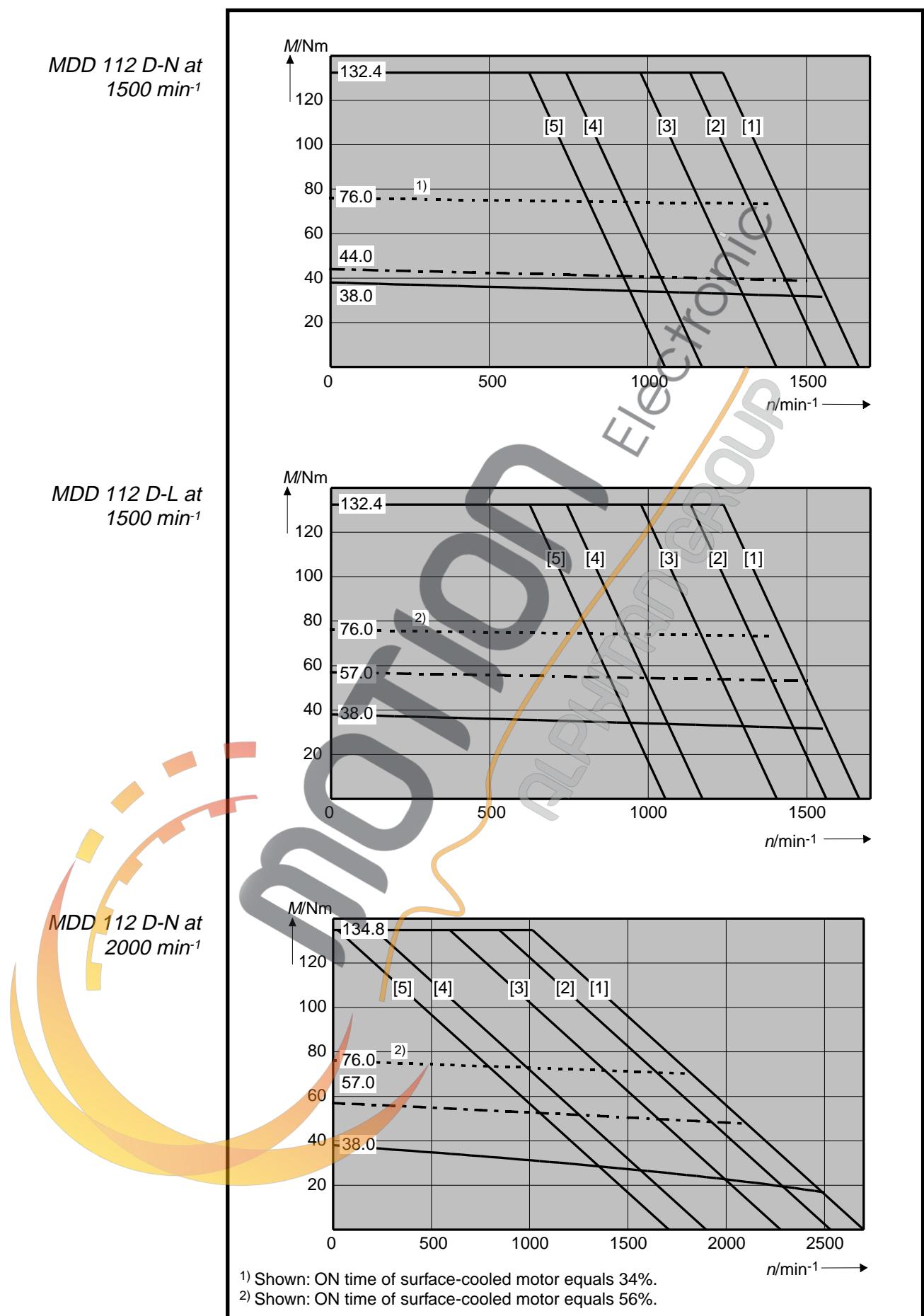


Fig 10.9: Torque-speed characteristics curve MDD 112

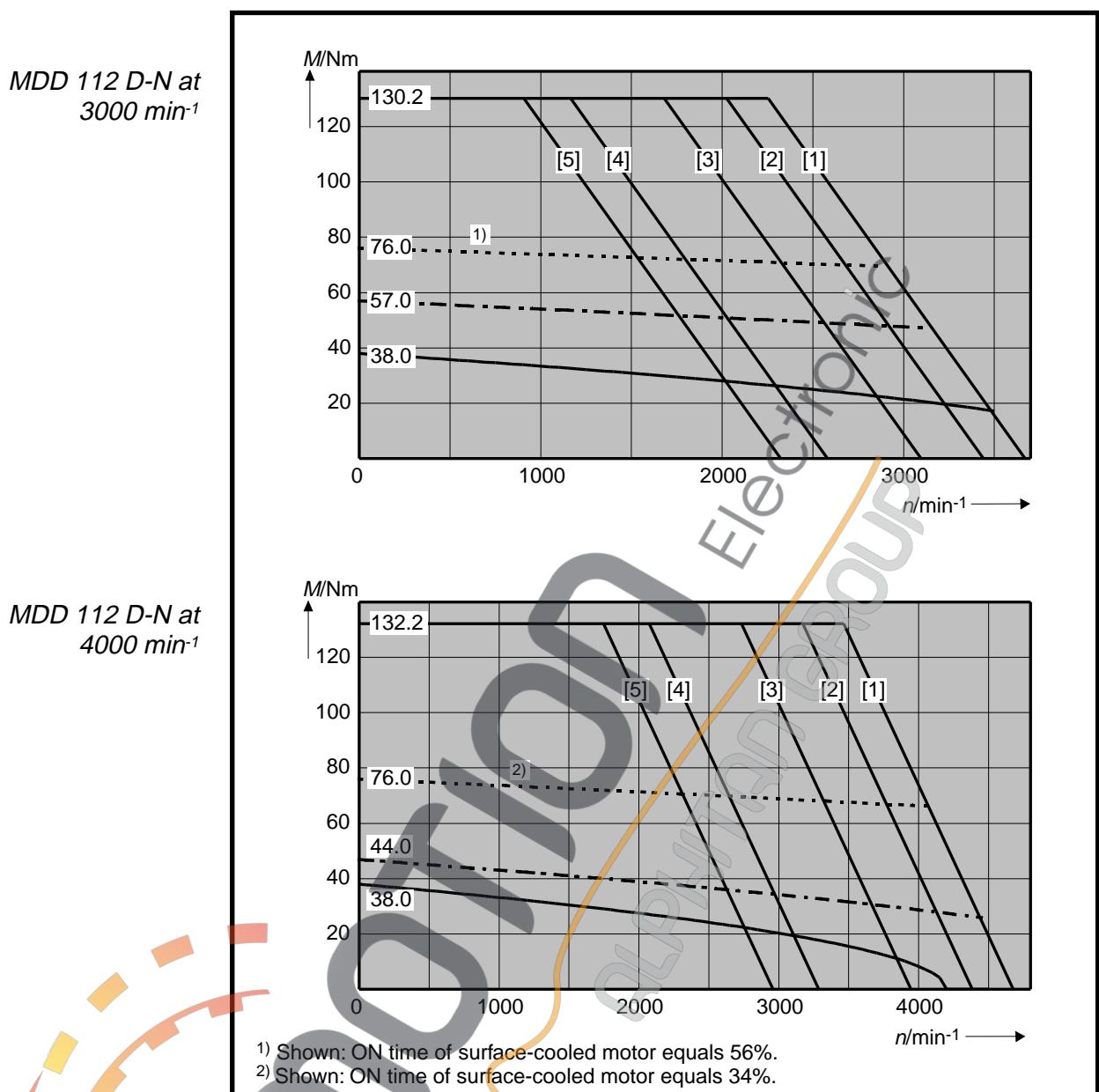
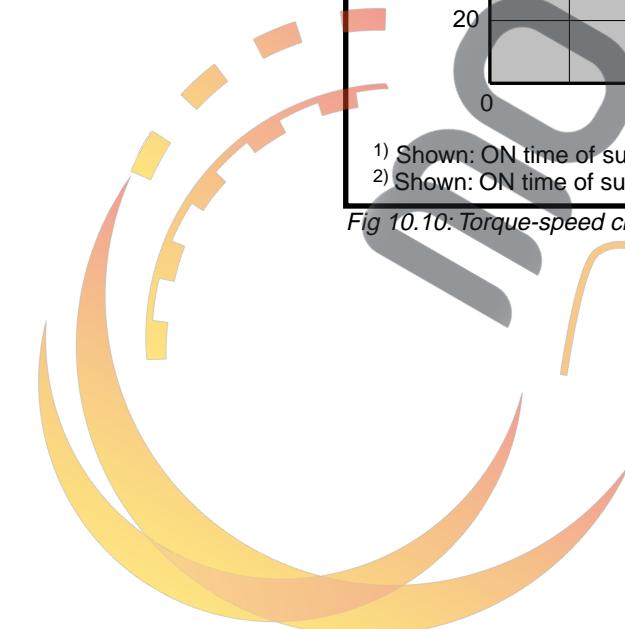


Fig 10.10: Torque-speed characteristics curve MDD 112



### 10.3. Shaft Load Capacity

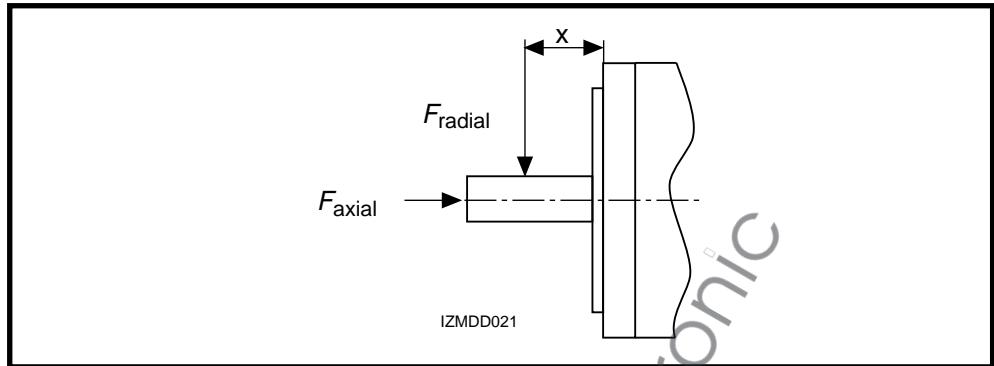


Fig 10.11: Shaft load

Permissible radial force

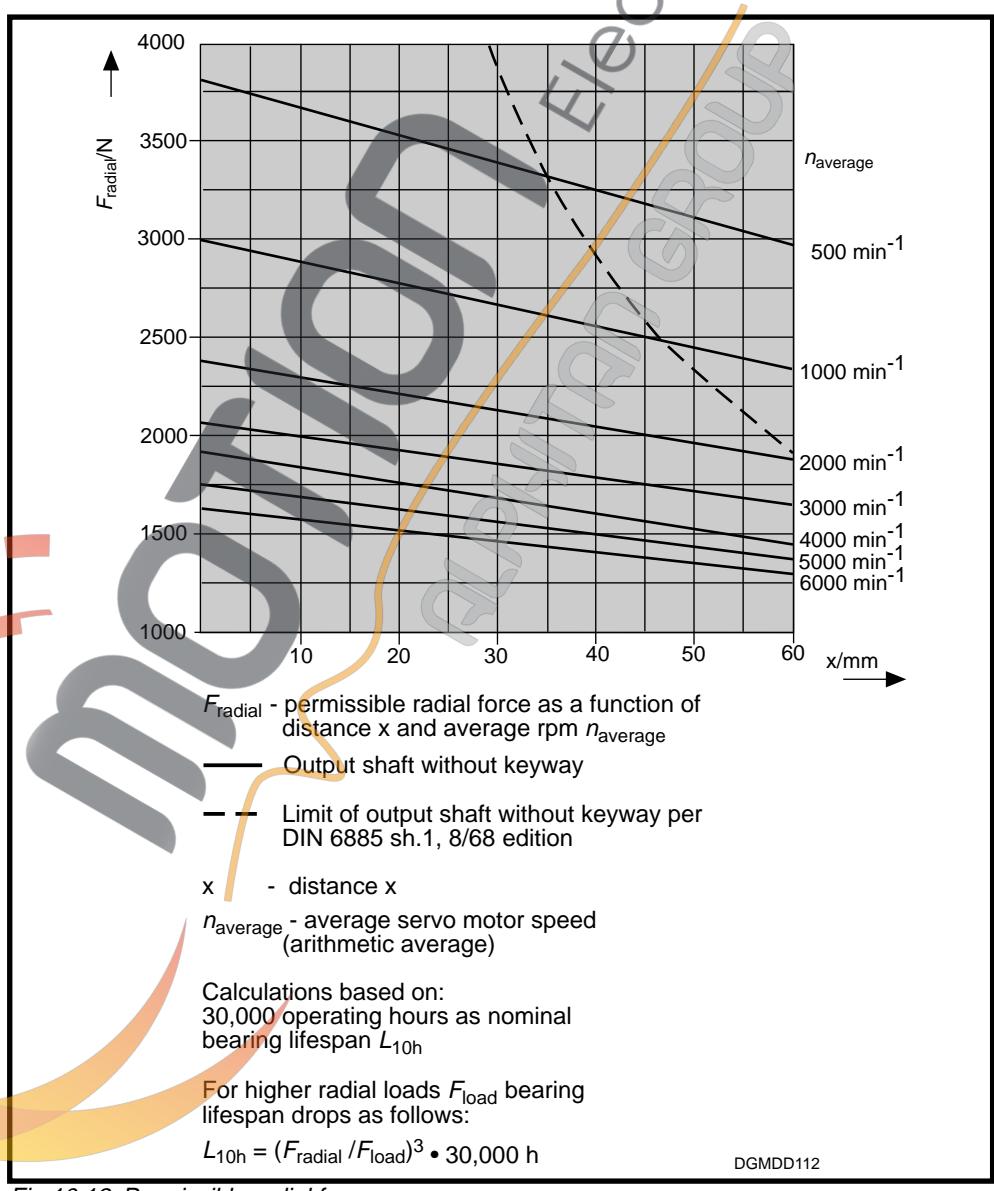
 $F_{\text{radial}}$ 

Fig 10.12: Permissible radial force

Permissible axial force

 $F_{\text{axial}}$ 

$$F_{\text{axial}} = 0.35 \cdot F_{\text{radial}}$$

 $F_{\text{axial}}$  - permissible axial force $F_{\text{radial}}$  - permissible radial force

## 10.4. Dimensional Data

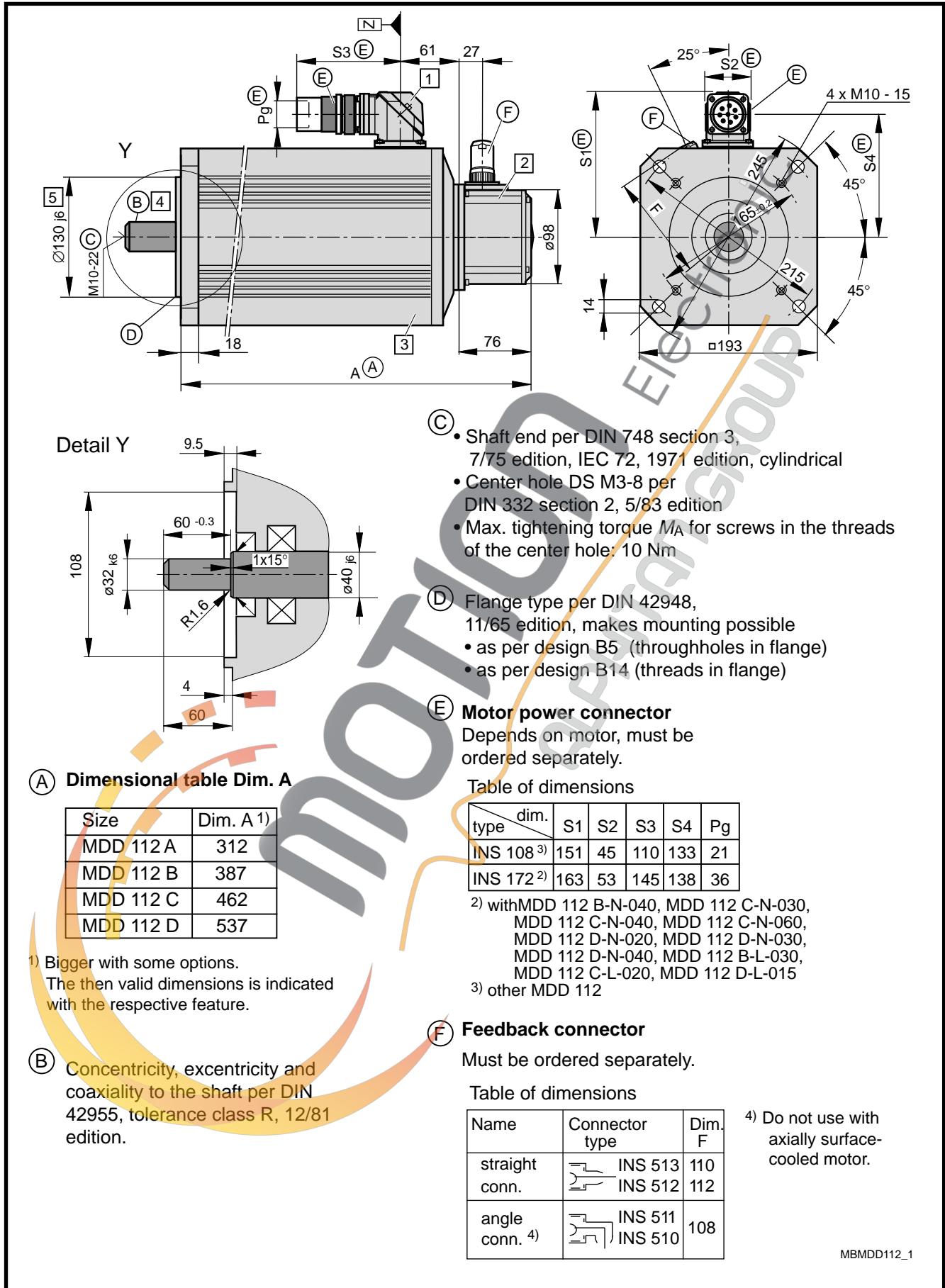


Fig 10.13: Dimensional data MDD 112

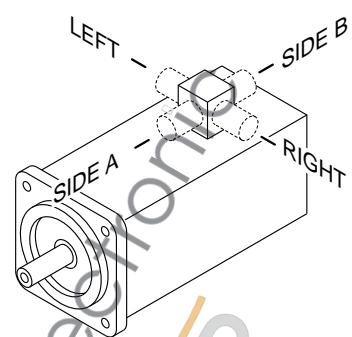
## Available Options

### 1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output direction is either:

- side A or
- side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other output direction are obtained by virtually turning the connector housing around the Z axis.



### 2 Motor feedback

- Digital servo feedback (DSF)
- Digital servo feedback (DSF) with integrated multiturn absolute encoder

The dimensions are identical.

### 3 Blocking brake

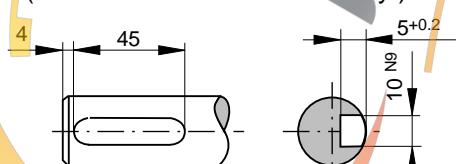
- without blocking brake
- with blocking brake: 14 Nm } The dimensions are identical.
- with blocking brake: 40 Nm (not available with MDD 112 A)
- with blocking brake: 60 Nm (not available with MDD 112)

#### Dimensional table for motor with holding brake of 40 Nm and 60 Nm

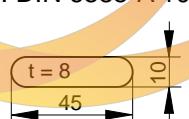
Size	Dim. A
MDD 112 B	437
MDD 112 C	512
MDD 112 D	587

### 4 Output shaft

- plain shaft (preferred type)
- with keyway per DIN 6885 sheet 1, 8/68 edition  
(Note: balanced with entire key!)



Matching key: DIN 6885-A 10 x 8 x 45



### 5 Special centering diameter

- $\varnothing 180$  j6

MBMDD112\_2

Fig 10.14: Dimensional data MDD 112 - available options

## 10.5. Available Versions

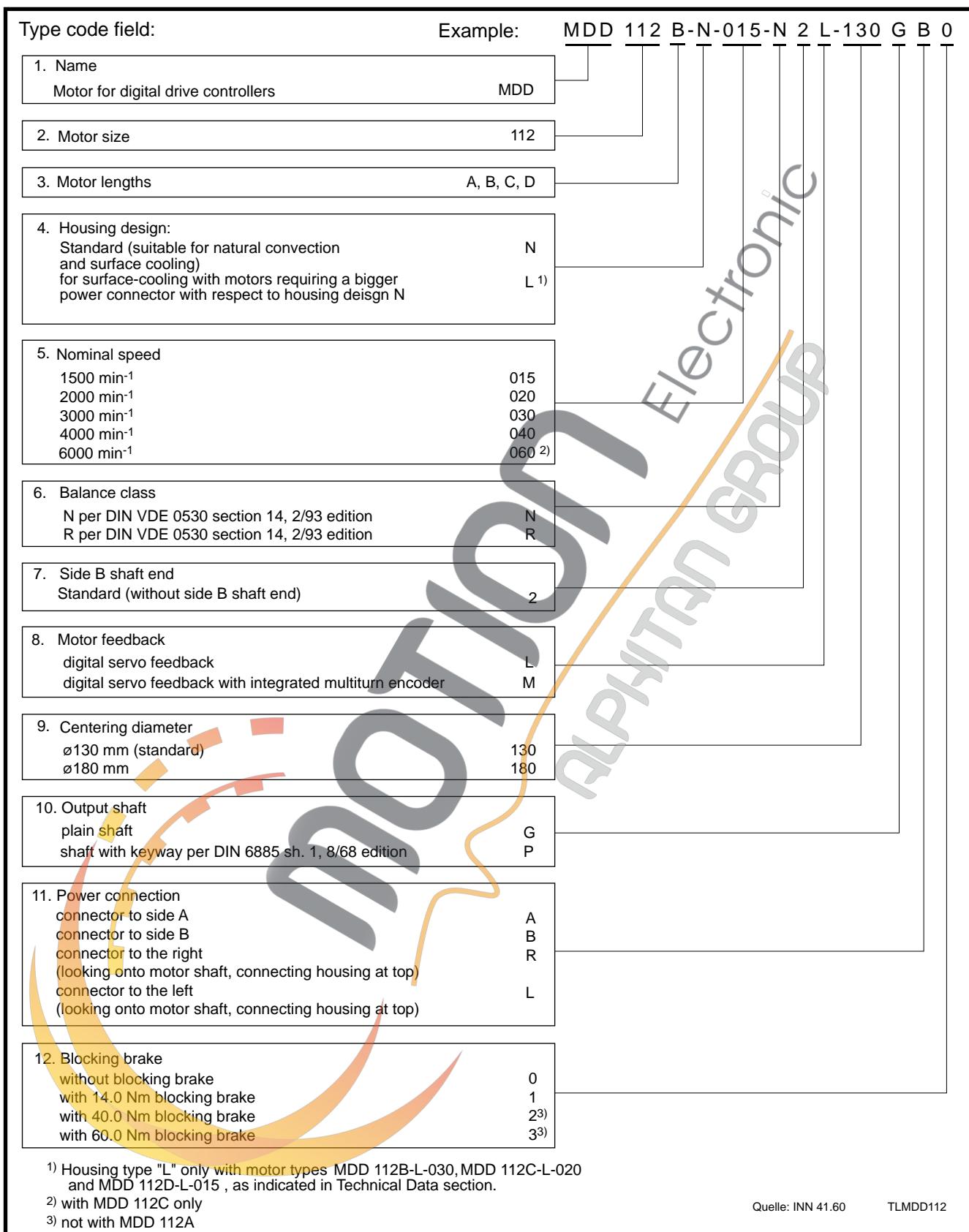


Fig 10.15: Type codes - MDD 112